

Cooling of Ions and \bar{p} with Magnetized Electrons*

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Binary collision model

- The motion of the center-of-mass (cm) and the relative motion do not separate.
- But for an ion mass M much larger than the electron mass m it is approximately:
 - cm-motion: $\vec{v}_i = \text{const} + O(\frac{m}{M})$, $\vec{V}_{cm} = \vec{v}_i + O(\frac{m}{M})$
 - relative motion: $\frac{d}{dt} m \vec{v}_r = -\nabla \Phi(r_r) - e(\vec{v}_r \times \vec{B}) - e(\vec{v}_i \times \vec{B}) + O(\frac{m}{M})$
 - cm-energy: $\frac{dE_{cm}}{dt} = \vec{V}_{cm} \cdot \frac{d}{dt} M \vec{V}_{cm} = -e \vec{v}_i \cdot (\vec{v}_r \times \vec{B}) + O(\frac{m}{M})$
 - integral of motion: $K = \frac{m}{2} \vec{v}_r^2 + \Phi(r_r) + e(\vec{v}_i \times \vec{B}) \cdot \vec{r}_r + O(\frac{m}{M})$

- In the binary collision model, the central physical observables are the velocity transfer $\Delta \vec{v}_r$ and the related energy transfer in a single collision

$$\Delta E_i \approx M \vec{v}_i \cdot \Delta \vec{v}_r = -m \vec{v}_i \cdot \Delta \vec{v}_r + M \vec{v}_i \cdot \Delta \vec{v}_{cm} = -m \vec{v}_i \cdot \Delta \vec{v}_r - \frac{m}{2} ((\vec{v}_r + \Delta \vec{v}_r)^2 - \vec{v}_r^2)$$

- The velocity and energy transfers, $\langle \Delta \vec{v}_r \rangle(\vec{v}_r, \vec{v}_i)$ and $\langle \Delta E_i \rangle(\vec{v}_r, \vec{v}_i)$, for a monochromatic beam of electrons results after integration with respect to the impact parameter b and the initial phase φ of the electron helix.

- Folding with the electron velocity distribution $f(\vec{v}_r)$ yields the drag force $\vec{F} = \vec{F}_\parallel + \vec{F}_\perp$ and the energy loss $dE_i/ds = \vec{F} \cdot \vec{v}_i/v_i$

Second-order perturbation treatment [6]

- The velocity transfer is calculated up to second order $O(Z^2)$ in the electron-ion interaction from the equations of motion for:

- the unperturbed helical motion of the electrons

$$m \ddot{\vec{v}}_0 + e(\vec{v}_0 \times \vec{B}) = -e(\vec{v}_i \times \vec{B}), \quad \dot{\vec{r}}_0 = \vec{v}_0$$

- the first order contribution

$$m \ddot{\vec{v}}_1 + e(\vec{v}_1 \times \vec{B}) = -\nabla \Phi(r_0), \quad \dot{\vec{r}}_1 = \vec{v}_1$$

- the second order correction

$$m \ddot{\vec{v}}_2 + e(\vec{v}_2 \times \vec{B}) = -[\nabla \Phi(|\vec{r}_0 + \vec{r}_1|) - \nabla \Phi(r_0)]$$

where $\vec{v}_r = \vec{v}_0 + \vec{v}_1 + \vec{v}_2$ and $\vec{r} = \vec{r}_0 + \vec{r}_1 + \vec{r}_2$

- Three regimes, characterized by Rutherford trajectories, stretched helices and tight helices, are identified where closed expressions for the velocity- and energy transfer can be derived. Interpolating between these regimes yields the final energy transfer.

- The averaging over the impact parameter (or distance of closest approach) b and the initial phase φ can be performed analytically with an upper cut-off b_{max} accounting for dynamic screening and a lower cut-off b_{min} excluding hard collisions.

Numerical treatment: Classical Trajectory Monte Carlo [2,7]

- numerical integration of the equations of motion

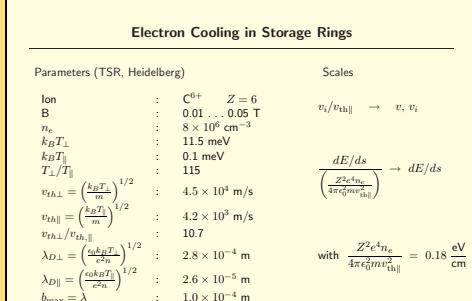
$$m \ddot{\vec{v}}_r = -\nabla \left[\frac{Z e^2}{r} \exp(-\frac{r}{\lambda}) \right] - e(\vec{v}_r \times \vec{B}) - e(\vec{v}_i \times \vec{B}), \quad \dot{\vec{r}} = \vec{v}_r$$

through the interaction region ($\sim \lambda$) for given initial values $\vec{v}_r, \vec{v}_i, \vec{b}, \varphi$

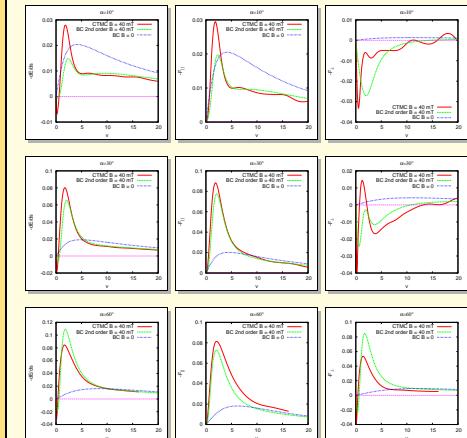
\Rightarrow velocity transfer $\Delta \vec{v}_r(\vec{v}_r, \vec{v}_i, \vec{b}, \varphi)$, energy transfer $\Delta E_i(\vec{v}_r, \vec{v}_i, \vec{b}, \varphi)$

- Monte Carlo sampling over \vec{b}, φ with $\approx 5 \times 10^4 \dots 4 \times 10^5$ trajectories per \vec{v}_r, \vec{v}_i

$$\Rightarrow \langle \Delta E_i(\vec{v}_r, \vec{v}_i) \rangle = \int d^2 b \int_0^{2\pi} \frac{d\varphi}{2\pi} \Delta E_i(\vec{v}_r, \vec{v}_i, \vec{b}, \varphi), \quad \langle \Delta \vec{v}_r(\vec{v}_r, \vec{v}_i) \rangle = \dots$$



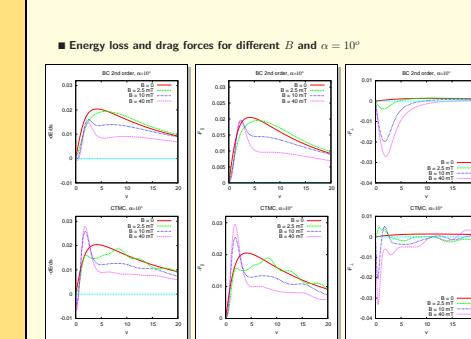
■ CTMC versus 2nd order BC for different α and $B = 40$ mT



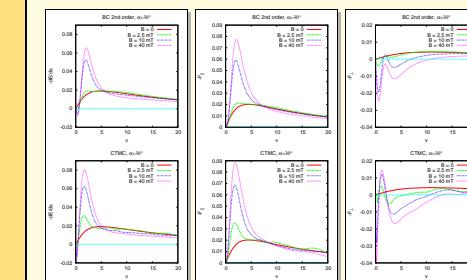
Very good qualitative agreement and a quantitative agreement within less than a factor 2 between the perturbation treatment (2nd order BC) and the numerical simulations (CTMC).

References

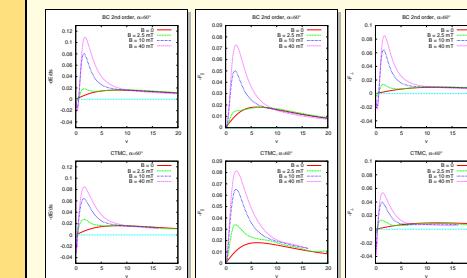
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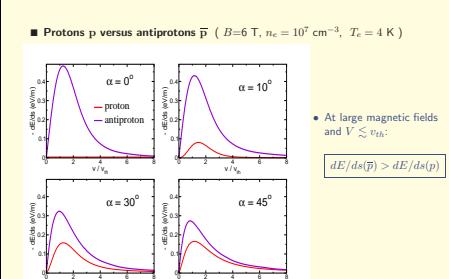
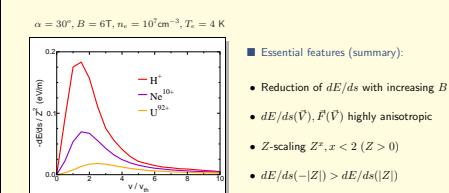
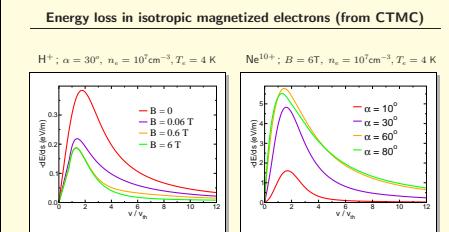
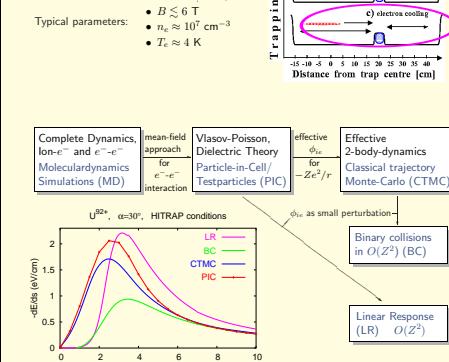
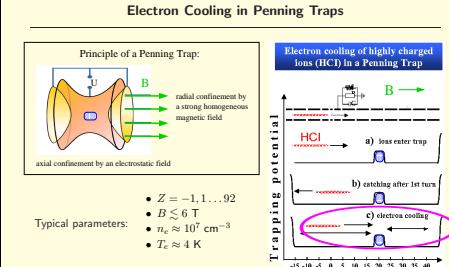
■ Energy loss and drag forces for different B and $\alpha = 30^\circ$



■ Energy loss and drag forces for different B and $\alpha = 60^\circ$



- 'Anti-cooling' for small v
- 'Anti-friction' in perpendicular direction for small v, v_\perp



- At large magnetic fields and $V \lesssim v_{th\perp}$: $dE/ds(\bar{p}) > dE/ds(p)$